

5996

POUFNE

PRZEMYSŁOWY INSTYTUT AUTOMATYKI I POMIARÓW
 MERA-PIAP
 Al. Jerozolimskie 202 02-222 Warszawa Telefon 23-70-81

Ośrodek Automatykacji Procesów Produkcji

4410

A

Poufne
egz. nr 1.

Główny wykonawca

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Nr zlecenia 9493

Etap 3 "Wykonanie zmian w oprogramowaniu układu sterowania IRb-6 dla wykonania badań prototypu części manipulacyjnej IRp-6L"

Zleceniodawca praca własna

Pracę rozpoczęto dnia 87.09.01

zakończono dnia 88.01.15

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d/s Automatyki

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Praca zawiera:

Rozdzielnik - ilość egz:

stron

Egz. 1 BOINTE

rysunków

Egz. 2 ~~OAP~~

fotografii

Egz. 3 ~~OAP~~

tabel

Egz. 4

tablic

Egz. 5

załączników 4

Egz. 6

Nr rejestr. 5996

Analiza deskrypcyjowa roboty przemysłowej, oprogramowanie, program sterujący

I 0 300 1,0

Analiza dokumentacyjna

Sprawozdanie zawiera tabulogram programu obliczania tablic współczynników korekcji do wykonywania ruchu przestoliniowego dla robota IRb-6L. Dołączono instrukcję posługiwania się programem i wydruki z wynikami obliczeń.

I -
I 0 300 1,0

Tytuły poprzednich sprawozdań

I 0 300 1,0
I 0 300 1,0
I 0 300 1,0

338.45: 62/63].002.1/2 Roboty przemysłowe

UKD

MAP-252/83-6000 -

Spis treści

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1. Wstęp.

Przedmiotem pracy była adaptacja standardowego oprogramowania robota IRb-6 dla robota IRb-6L z wydłużonym ramieniem. W związku ze zmianą modelu kinematycznego robota, konieczne było wprowadzenie zmian w programie sterującym robota IRb-6 polegających na zmianie tablic korekcji wykorzystywanych przy ruchu manipulatora w osiach α i θ . Tablice te o nazwach AKTAB i TKTAB zawierają odpowiednio 454 i 382 współczynniki korekcji, przy czym jedno ośmiobitowe słowo zawiera dwie poprawki /4 starsze i 4 młodsze bity/. Do obliczenia nowych tablic został wykorzystany program firmy ASEA o nazwie "Program for calculation and control of the correction tables for α and θ axes" napisany w języku Fortran IV. Program, ten został zaimplementowany na komputer IBM PC.

Poprawność działania programu sprawdzono obliczając tablice korekcji dla manipulatora IRb-6 i porównując je z tablicami zawartymi w programie sterującym firmy ASEA dla IRb-6.

Dołączono tabulegram programu obliczeń /dolne i górne części tablic/, oraz wydruk zawierający wyniki obliczeń dla IRb-6 i IRp-6L.

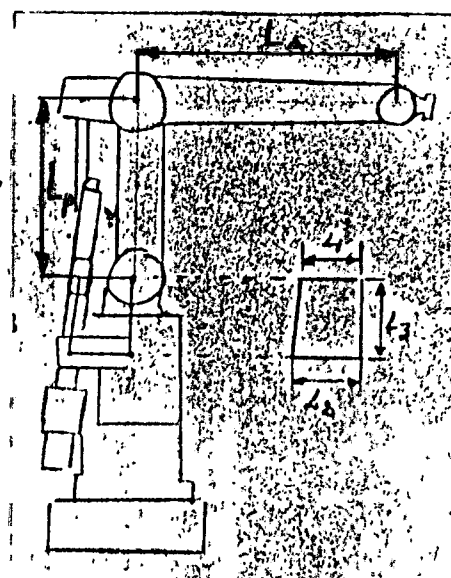
4

2. Instrukcja ładowania i uruchamiania programów.

Programy obliczające górne i dolne części tablic są wykonywane po podaniu komend KORG i KORD /KORG - górne części tablic korekcji, KORD - dolne części tablic korekcji/. Ze względu na wykorzystanie kompilatora firmy Microseft po uruchomieniu programów należy podać nazwy urządzeń wejściowego i wyjściowego /odpowiednio numery 5 i 6/.

Dane wejściowe programu są wprowadzane w następującej kolejności:

- L_1
- L_2
- L_3
- $\theta_0 / = 10^\circ$ dla IRb - 60, 15° IRb-6/
s /skok śr./
- L_p
- L_A
- n /liczba inkrem. na obr. sil/
- α min
- α max
- θ min
- θ max
- R_0 /IRb-6 $R_0=Z_0=0$, IRb-60 $R_0=80, Z_0=400$ mm/
- Z_0



Dla IRb-6 i IRp-6L parametry wejściowe mają następujące wartości:

	IRb-6	IRp-6L
L_1	140	140
L_2	155	155
L_3	183	183
θ_0	15	15
s	5	5
L_p	450	670
L_A	670	670
n	200	200
α min	0	0
α max	25	25
θ min	0	0
θ max	40	40

	IRb-6	IRp-6L
R_0	0	0
Z_0	0	0

Dla dolnej części tablic α min, α max, θ min, θ max wynoszą odpowiednio: 40, 0, 0, - 40.

Wyniki obliczeń w zależności od zadeklarowanego urządzenia wyjściowego są wprowadzane na ekran monitora, drukarkę lub są zapisywane w zbiorze dyskowym.

3. Załączniki.

Załączniki zawierają kolejno:

- tabulogramy programów KORG i KORD
- wyniki obliczeń górnych części tablic dla IRb-6 i IRp-6L
- wyniki obliczeń dolnych części tablic dla IRb-6 i IRp-6L.

```

C
C
C           A S E A
C
C   Program for calculation and control of the correction tables
C   for  $\alpha$  and  $\theta$  axes.
C
C   Program oblicza gorne czesci tablic korekcji
C
C           Main program
C           -----
C
C   real a11,a12,a13,vnoll,stig,alp,ala,anvarv,astart
C   real astopp,tstart,tstopp,rnoll,znoll,rmin,rmax,zmin,zmax
C   dimension ialfak(2,999),itetak(2,999),akont(10,12),tkont(10,12)
C   common s,am,v1,v2,x1,x2,x3,x4
C   data pi,rad/3.141593,0.01745329/
C
C
C
C   write(6,3000)
3000 format(' a11,a12,a13,vnoll,stig,alp,ala,anvarv,astart',
1' ,astopp,tstart,tstopp,rnoll,znoll')
read(5,3001) a11,a12,a13,vnoll,stig,alp,ala,anvarv,astart
read(5,3001) astopp,tstart,tstopp,rnoll,znoll
3001 format(f12.3)
C
C   rmin=r(astart*rad,tstart*rad,ala,alp)
C   rmax=r(astopp*rad,tstopp*rad,ala,alp)
C   zmax=z(astopp*rad,tstart*rad,ala,alp)
C   zmin=z(astart*rad,tstopp*rad,ala,alp)
C
C
C
C   s=stig
C   am=anvarv
C   v1=vnoll*rad
C   v2=atan(a12/a13)
C   x1=2.*a11*sqrt(a12**2+a13**2)
C   x2=a11**2+a12**2+a13**2
C   x3=sqrt(x2-x1*sin(v2))
C   x4=sqrt(x2-x1*sin(v2-v1))
C   bstart=rad*astart
C   bstopp=rad*astopp
C   ustart=rad*tstart
C   ustopp=rad*tstopp
C   do 15 i=1,999
C   ialfak(1,i)=0
C   ialfak(2,i)=0
C   itetak(1,i)=0
C   itetak(2,i)=0
15 continue
kopp=1
C
C   The tables should be corect on the two lines crrossing the
C   point (R0,Z0)
C
C   Calculation of table for vertical motion
C
C
C   call nalfa(bstart,am1)
C   call nalfa(bstopp,am2)
C   m11=sign(int(abs(am1)/16.+0.94),int(am1))
C   m12=sign(int(abs(am2)/16.+0.94),int(am2))
C   m1=16*m11
C   m2=16*m12
C   am1=float(m1)
C   am2=float(m2)
C   ka=m12-m11
C   call alfav(am1,cstart)
C   teta=t(rnoll,cstart,ala,alp)
C   call nteta(teta,tn1)
C   itetak(1,1)=m1
C   do 10 i=1,ka
C   alfan=am1+float(16*i)
C   call alfav(alfan,alfa)
C   teta=t(rnoll,alfa,ala,alp)
C   call nteta(teta,tn)
C   itetak(1,i+1)=ifix(alfan)
C   tn2=tn-tn1
C   itetak(2,i)=ifix(sign(aint(abs(tn2)+0.5),tn2))
C   tn1=tn
C   il=int(float(ka+1)/125.+0.999)
10 continue
C
C   Calculation of table for horisontal motion
C
C
C   call nteta(ustart,tn1)

```



```

n11=sign(int(abs(tn1)/16.+0.94),int(tn1))
n12=sign(int(abs(tn2)/16.+0.94),int(tn2))
n1=16*n11
n2=16*n12
tn1=float(n1)
tn2=float(n2)
kt=n12-n11
call tetav(tn1,vstart)
alfa=a(znoll,vstart,ala,alp)
call nalfa(alfa,an1)
ialfak(1,1)=n1
do 20 i=1,kt
tetan=tn1+float(16*i)
call tetav(tetan,teta)
alfa=a(znoll,teta,ala,alp)
call nalfa(alfa,an)
ialfak(1,i+1)=ifix(tetan)
an2=an-an1
ialfak(2,i)=ifix(sign(aint(abs(an2)+0.5),an2))
an1=an
i2=int(float(kt+1)/125.+0.999)
20 continue
C
C Control of table for vertical motion
C
C
do 220 i=1,5
rstep=rmin+(rmax-rmin)/4.*float(i-1)
call alfav(am2,cstart)
teta=t(rstep,cstart,ala,alp)
zeta=z(cstart,teta,ala,alp)
call nteta(teta,tn)
tkont(i,1)=zeta
tkont(i+5,1)=r(cstart,teta,ala,alp)-rstep
ka1=int(float(ka)/11.)
do 220 j=1,11
k=ka+1-ka1*j
an=float(itetak(1,k))
do 210 l=1,ka1
m=k+ka1-l
tn=tn-float(itetak(2,m))
210 continue
if(tn.gt.tn2) go to 215
call alfav(an,alfa)
call tetav(tn,teta)
ra=r(alfa,teta,ala,alp)
zeta=z(alfa,teta,ala,alp)
rdel=ra-rstep
tkont(i,j+1)=zeta
tkont(i+5,j+1)=rdel
go to 220
215 continue
tkont(i,j+1)=1.e8
220 continue
C
C Control of table for horizontal motion
C
C
do 240 i=1,5
zstep=zmax-(zmax-zmin)/4.*float(i-1)
call tetav(tn1,vstart)
alfa=a(zstep,vstart,ala,alp)
ra=r(alfa,vstart,ala,alp)
call nalfa(alfa,an)
akont(i,1)=ra
akont(i+5,1)=z(alfa,vstart,ala,alp)-zstep
kt1=int(float(kt)/11.)
do 240 j=1,11
k=1+kt1*j
tn=float(ialfak(1,k))
do 230 l=1,kt1
m=k-(kt1+1)+l
an=an+float(ialfak(2,m))
230 continue
if ((an.gt.am2).or.(an.lt.am1)) go to 235
call alfav(an,alfa)
call tetav(tn,teta)
ra=r(alfa,teta,ala,alp)
zeta=z(alfa,teta,ala,alp)
zdel=zeta-zstep
akont(i,j+1)=ra
akont(i+5,j+1)=zdel
go to 240
235 continue
akont(i,j+1)=1.e8
240 continue
C
C
C Printing of tables
C
C
ntal=ak+1
do 60 i=1,11
write(6,1000) i

```

```

        if(i.ne.1) write(6,1050)
        write(6,1020)
        j=125*(i-1)
        do 60 k=1,25
            l=k+j-25
            write(6,1030) (itetak(1,25*m+1),m=1,5)
            write(6,1040) (itetak(2,25*m+1),m=1,5)
60      continue
C
C
C
        nta1=kt+1
        do 100 i=1,i2
            write(6,1100) i
            if(i.eq.1) write(6,1110) nta1
            if(i.ne.1) write(6,1050)
            write(6,1120)
            j=125*(i-1)
            do 100 k=1,25
                l=k+j-25
                write(6,1030) (ialfak(1,25*m+1),m=1,5)
                write(6,1040) (ialfak(2,25*m+1),m=1,5)
100      continue
C
C
C      Printing of control vertikal
C
C
        do 110 i=1,5
            if(i.eq.1) write(6,1150)
            if(i.eq.3.or.i.eq.5) write(6,1190)
            rstep=rmin+(rmax-rmin)/4.*float(i-1)
            write(6,1160) rstep
            do 110 j=1,i2
                if(tkont(i,j).gt.1.e6) go to 105
                if(j.eq.1) write(6,1170) tkont(i,j),tkont(i+5,j)
                if(j.ne.1) write(6,1180) tkont(i,j),tkont(i+5,j)
                go to 110
105      continue
            write(6,1260)
110      continue
C
C
C      Printing of control horizontal
C
C
        do 120 i=1,5
            if(i.eq.1) write(6,1200)
            if(i.eq.1.or.i.eq.3.or.i.eq.7) write(6,1190)
            zstep=zmax-(zmax-zmin)/4.*float(i-1)
            write(6,1210) zstep
            do 120 j=1,i2
                if(akont(i,j).gt.1.e6) go to 115
                if(j.eq.1) write(6,1220) akont(i,j),akont(i+5,j)
                if(j.ne.1) write(6,1180) akont(i,j),akont(i+5,j)
                go to 120
115      continue
            write(6,1120)
120      continue
C
C
C      Calculation of nalfa & nteta as a function of respective angle
C
C
        write(6,1230)
        j=ifix(astopp-astart)+1
        k=ifix(tstopp-tstart)+1
        l=max0(j,k)
        do 130 i=1,l
            ialfa=ifix(astopp)+i-1
            iteta=ifix(tstopp)+i-1
            alfa=rad*float(ialfa)
            teta=rad*float(iteta)
            call nalfa(alfa,an)
            call nteta(teta,tn)
            ian=ifix(an)
            itn=ifix(tn)
            if(i.le.j.and.i.le.k) write(6,1240) ialfa,ian,iteta,itn
            if(i.gt.j) write(6,1250) iteta,itn
            if(i.gt.k) write(6,1255) ialfa,ian
130      continue
25      continue
C
C
C
1000 format(1h1,'korrektionstabell for korning vertikalt',
12ix,'sid',i2)
1010 format(//1x,'nalfa=laget hos alfa-motorn fran alfa=0',
11x,'(inkrement)//1x,'dif =erforderling',
21x,'korection hos teta-motorn//1x,'tabellen',
31x,'innehaeller',i4,'nalfa-varde')
1020 format(//1x,'nalfa dif'//)
1030 format(i6,4(i14))

```

```

1050 format(////)
C
C
1100 format(1h1,'korrektionstabell for korning horisontellt',
118x,'sid',i2)
1110 format(//1x,'nteta=laget hos teta-motorn fran teta=0',
11x,'(inkrement)/1x,'dif =erforderling',
2' korrektion hos alfa-motorn',1x,'tabellen',
3' innehaller',i4,'nteta-varde')
1120 format(//' nteta dif'//)
1130 format(i6,3(i14))
1140 format(i10,3(i14))
C
1150 format(1h1,'radiell avvikelse delr i mm vid korning'
1' vertikalt med korrektion enligt den be-
2' raknade tabellen')
1160 format(///' radi=',f6.0//)
1170 format(//' z=',f8.2,2x,'delr=',f6.2)
1180 format(//1x,f10.2,2x,f11.2)
1190 format(1h1////)
1200 format(1h1,'vertikal avvikelse delz i mm vid korning'
1' horisontellt med korrektion enligt den be-
2' raknade tabellen')
1210 format(//1x,'z=',f6.0//)
1220 format(//1x,'r=',f8.2,2x,'delz=',f6.2)
1230 format(1h1,'antal inkrement nalfa och nteta som funtion'
1' av resp vinkel'
2'//1x,'alfa',6x,'nalfa',10x,'teta',6x,'nteta'//)
1240 format(i4,7x,i5,10x,i3,7x,i5)
1250 format(26x,i3,7x,i5)
1255 format(i4,7x,i5)
1260 format(/9x,'ut',i1x,'ut')
2000 continue
stop
end

C
C
C
C
C
subroutine nalfa(alfa,an)
common s,am,v1,v2,x1,x2,x3,x4
an=am/s*(x3-sqrt(x2-x1*sin(v2+alfa)))
return
end

C
C
C
C
C
subroutine nteta(teta,tn)
common s,am,v1,v2,x1,x2,x3,x4
tn=am/s*(sqrt(x2-x1*sin(v2-v1-teta))-x4)
return
end

C
C
C
C
C
subroutine alfav(alfan,a)
common s,am,v1,v2,x1,x2,x3,x4
a1=x2-(x3-s/am*alfan)**2
a=-v2+atan(a1/sqrt(x1**2-a1**2))
return
end

C
C
C
C
C
subroutine tetav(tetan,t)
common s,am,v1,v2,x1,x2,x3,x4
b=x2-(s/am*tetan+x4)**2
t=v2-v1-atan(b/sqrt(x1**2-b**2))
return
end

C
C
C
C
C
real function t(r,a,ala,alp)
t=atan((r+ala*(1.-cos(a)))/sqrt(alp**2-(r+ala*(1.-cos(a)))
1**2))
return
end
real function a(z,t,ala,alp)
a=atan((z+alp*(1.-cos(t)))/sqrt(ala**2-(z+alp*(1.-cos(t)))
1**2))
return
end
real function r(alfa,teta,ala,alp)
r=alp*sin(teta)-ala*(1.-cos(alfa))
return
end
real function z(alfa,teta,ala,alp)
z=ala*sin(alfa)-alp*(1.-cos(teta))
return
end

```

```

C
C
C      A S E A
C
C   Program for calculation and control of the correction tables
C   for  $\alpha$  and  $\theta$  axes.
C
C   Program oblicza dolne czesci tablic korekcji
C
C           Main program
C           -----
C
C
C   real all,al2,al3,vnoll,stig,alp,ala,anvarv,astart
C   real astopp,tstart,tstopp,rnoll,znoll,rmin,rmax,zmin,zmax
C   dimension ialfak(2,999),itetak(2,999),akont(10,12),tkont(10,12)
C   common s,am,v1,v2,x1,x2,x3,x4
C   data pi,rad/3.141593,0.01745329/
C
C
C
C   write(6,3000)
3000 format(' all,al2,al3,vnoll,stig,alp,ala,anvarv,astart',
1' ,astopp,tstart,tstopp,rnoll,znoll')
read(5,3001) all,al2,al3,vnoll,stig,alp,ala,anvarv,astart
read(5,3001) astopp,tstart,tstopp,rnoll,znoll
3001 format(f12.3)
rmin=r(astart*rad,tstart*rad,ala,alp)
rmax=r(astopp*rad,tstopp*rad,ala,alp)
zmax=z(astopp*rad,tstopp*rad,ala,alp)
zmin=z(astart*rad,tstart*rad,ala,alp)
C
C
C
C   s=stig
C   am=anvarv
C   v1=vnoll*rad
C   v2=atan(al2/al3)
C   x1=2.*all*sqrt(al2**2+al3**2)
C   x2=all**2+al2**2+al3**2
C   x3=sqrt(x2-x1*sin(v2))
C   x4=sqrt(x2-x1*sin(v2-v1))
C   bstart=rad*astart
C   bstopp=rad*astopp
C   ustart=rad*tstart
C   ustopp=rad*tstopp
C   do 15 i=1,999
C   ialfak(1,i)=0
C   ialfak(2,i)=0
C   itetak(1,i)=0
C   itetak(2,i)=0
15 continue
C   kopp=1
C
C
C   The tables should be corect on the two lines crrossing the
C   point (R0,Z0)
C
C   Calculation of table for vertical motion
C
C
C   call nalfa(bstart,am1)
C   call nalfa(bstopp,am2)
C   m1=sign(int(abs(am1)/16.+0.94),int(am1))
C   m2=sign(int(abs(am2)/16.+0.94),int(am2))
C   m1=16*m1
C   m2=16*m2
C   am1=float(m1)
C   am2=float(m2)
C   ka=m2-m1
C   call alfav(am1,cstart)
C   teta=t(rnoll,cstart,ala,alp)
C   call nteta(teta,tn1)
C   itetak(1,1)=m1
C   do 10 i=1,ka
C   alfan=am1+float(16*i)
C   call alfav(alfan,alfa)
C   teta=t(rnoll,alfa,ala,alp)
C   call nteta(teta,tn)
C   itetak(1,i+1)=ifix(alfan)
C   tn2=tn-tn1
C   itetak(2,i)=ifix(sign(aint(abs(tn2)+0.5),tn2))
C   tn=tn
C   ii=int(float(ka+1)/125.+0.999)
10 continue
C
C
C   Calculation of table for horisontal motion
C
C   call nteta(ustart,tn1)

```

```

n1=sign(int(abs(tn1)/16.+0.94),int(tn1))
n12=sign(int(abs(tn2)/16.+0.94),int(tn2))
n1=16*n1
n2=16*n12
tn1=float(n1)
tn2=float(n2)
kt=n12-n1
call tetav(tn1,vstart)
alfa=a(znoll,vstart,ala,alp)
call nalfa(alfa,an1)
ialfak(1,1)=n1
do 20 i=1,kt
tetan=tn1+float(16*i)
call tetav(tetan,teta)
alfa=a(znoll,teta,ala,alp)
call nalfa(alfa,an)
ialfak(1,i+1)=ifix(tetan)
an2=an-an1
ialfak(2,i)=ifix(sign(aint(abs(an2)+0.5),an2))
an1=an
i2=int(float(kt+1)/125.+0.999)
20 continue
c
c
c Control of table for vertical motion
c
c
do 220 i=1,5
rstep=rmin+(rmax-rmin)/4.*float(i-1)
call alfav(am2,cstart)
c
teta=t(rstep,cstart,ala,alp)
zeta=z(cstart,teta,ala,alp)
call nteta(teta,tn)
tkont(i,1)=zeta
tkont(i+5,1)=r(cstart,teta,ala,alp)-rstep
kal=int(float(ka)/11.)
do 220 j=1,11
k=ka+i-kal*j
an=float(itetak(1,k))
do 210 l=1,kal
m=k+kal-l
210 tn=tn-float(itetak(2,m))
continue
if(tn.gt.tn2) go to 215
call alfav(an,alfa)
call tetav(tn,teta)
ra=r(alfa,teta,ala,alp)
zeta=z(alfa,teta,ala,alp)
rdel=ra-rstep
tkont(i,j+1)=zeta
tkont(i+5,j+1)=rdel
go to 220
215 continue
tkont(i,j+1)=1.e8
220 continue
c
c
c Control of table for horisontal motion
c
c
do 240 i=1,5
zstep=zmax-(zmax-zmin)/4.*float(i-1)
call tetav(tn1,vstart)
alfa=a(zstep,vstart,ala,alp)
ra=r(alfa,vstart,ala,alp)
call nalfa(alfa,an)
akont(i,1)=ra
akont(i+5,1)=z(alfa,vstart,ala,alp)-zstep
kt1=int(float(kt)/11.)
do 240 j=1,11
k=1+kt1*j
tn=float(ialfak(1,k))
do 230 l=1,kt1
m=k-(kt1+1)+l
230 an=an+float(ialfak(2,m))
continue
if((an.gt.am2).or.(an.lt.am1)) go to 235
call alfav(an,alfa)
call tetav(tn,teta)
ra=r(alfa,teta,ala,alp)
zeta=z(alfa,teta,ala,alp)
zdel=zeta-zstep
akont(i,j+1)=ra
akont(i+5,j+1)=zdel
go to 240
235 continue
akont(i,j+1)=1.e8
240 continue
c
c
c Printing of tables
c

```

```

c      nta1=ak+1
      do 60 i=1,i1
      write(6,1000) i
      if(i.eq.1) write(6,1010) nta1
      if(i.ne.1) write(6,1050)
      write(6,1020)
      j=125*(i-1)
      do 60 k=1,25
      l=k+j-25
      write(6,1030) (itetak(1,25*m+1),m=1,5)
      write(6,1040) (itetak(2,25*m+1),m=1,5)
60    continue
c
c
c
c      nta1=kt+1
      do 100 i=1,i2
      write(6,1100) i
      if(i.eq.1) write(6,1110) nta1
      if(i.ne.1) write(6,1050)
      write(6,1120)
      j=125*(i-1)
      do 100 k=1,25
      l=k+j-25
      write(6,1030) (ialfak(1,25*m+1),m=1,5)
      write(6,1040) (ialfak(2,25*m+1),m=1,5)
100   continue
c
c
c      Printing of control vertikal
c
c
c      do 110 i=1,5
      if(i.eq.1) write(6,1150)
      if(i.eq.3.or.i.eq.5) write(6,1190)
      rstep=rmin*(rmax-rmin)/4.*float(i-1)
      write(6,1160) rstep
      do 110 j=1,12
      if(tkont(i,j).gt.1.e6) go to 105
      if(j.eq.1) write(6,1170) tkont(i,j),tkont(i+5,j)
      if(j.ne.1) write(6,1180) tkont(i,j),tkont(i+5,j)
      go to 110
105   continue
      write(6,1260)
110   continue
c
c
c
c      Printing of control horizontal
c
c
c
c      do 120 i=1,5
      if(i.eq.1) write(6,1200)
      if(i.eq.1.or.i.eq.5.or.i.eq.7) write(6,1190)
      zstep=zmax-(zmax-zmin)/4.*float(i-1)
      write(6,1210) zstep
      do 120 j=1,12
      if(akont(i,j).gt.1.e6) go to 115
      if(j.eq.1) write(6,1220) akont(i,j),akont(i+5,j)
      if(j.ne.1) write(6,1180) akont(i,j),akont(i+5,j)
      go to 120
115   continue
      write(6,1120)
120   continue
c
c
c
c      Calculation of nalfa & nteta as a function of respective angle
c
c
c      write(6,1230)
      j=ifix(astopp-astart)+1
      k=ifix(tstopp-tstart)+1
      l=max0(j,k)
      do 130 i=1,l
      ialfa=ifix(astopp)+i-1
      iteta=ifix(tstopp)+i-1
      alfa=rad*float(ialfa)
      teta=rad*float(iteta)
      call nalfa(alfa,an)
      call nteta(teta,tn)
      ian=ifix(an)
      itn=ifix(tn)
      if(i.le.j.and.i.le.k) write(6,1240) ialfa,ian,iteta,itn
      if(i.gt.j) write(6,1250) iteta,itn
      if(i.gt.k) write(6,1255) ialfa,ian
130   continue
25   continue
c
c
c
1000 format(1h1,'korrektions tabell for korning vertikalt',
121x,'sid',i2)
1010 format(//1x,'nalfa=laget hos alfa-motorn fran alfa=0',
11x,'(inkrement)'/1x,'dif =erforderling',

```

```

2..x,'(orection 105 beta-motorn',ix,'tabellen',
3ix,'inneholder',i4,'nalfa-varden')
1020 format(//ix,'nalfa dif'//)
1030 format(i6,4(i14))
1040 format(i10,4(i14))
1050 format(/////)
C
C
1100 format(ih1,'korrektionstabell for korning horisontellt',
118x,'sid',i2)
1110 format(//ix,'nteta=laget hos teta-motorn fran teta=0',
1ix,'(inkrement)'//ix,'dif =erforderling',
2' korrektion hos alfa-motorn',ix,'tabellen',
3' inneholder',i4,'nteta-varden')
1120 format(//nteta dif'//)
1130 format(i6,3(i14))
1140 format(i10,3(i14))
C
1150 format(ih1,'radiell avvikelse delr i mm vid korning'
1/' vertikalt med korrektion enligt den be-'
2/' raknade tabellen'//)
1160 format(//radien',f6.0//)
1170 format(//z',f8.2,2x,'delr',f6.2)
1180 format(//ix,f10.2,2x,f11.2)
1190 format(ih1'//)
1200 format(ih1,' vertikal avvikelse delz i mm vid korning'
1/' horisontellt med korrektion enligt den be-'
2/' raknade tabellen'//)
1210 format(//ix,'z',f6.0//)
1220 format(//ix,'r',f8.2,2x,'delz',f6.2)
1230 format(ih1,'antal inkrement nalfa och nteta som funtion'
1/' av resp vinkel'
2///ix,'alfa',6x,'nalfa',10x,'teta',6x,'nteta'//)
1240 format(i4,7x,i5,10x,i3,7x,i5)
1250 format(26x,i3,7x,i5)
1255 format(i4,7x,i5)
1260 format(//9x,'ut',11x,'ut')
2000 continue
stop
end
C
C
C
C
subroutine nalfa(alfa,an)
common s,am,v1,v2,x1,x2,x3,x4
an=am/s*(x3-sqrt(x2-x1*sin(v2-alfa)))
return
end
C
C
C
C
subroutine nteta(teta,tn)
common s,am,v1,v2,x1,x2,x3,x4
tn=am/s*(sqrt(x2-x1*sin(v2-v1+teta))-x4)
return
end
C
C
C
C
subroutine alfav(alfan,a)
common s,am,v1,v2,x1,x2,x3,x4
a1=x2-(x3-s/am*alfan)**2
a=-v2+atan(a1/sqrt(x1**2-a1**2))
return
end
C
C
C
C
subroutine tetav(tetan,t)
common s,am,v1,v2,x1,x2,x3,x4
b=x2-(s/am*tetan+x4)**2
t=v2-v1-atan(b/sqrt(x1**2-b**2))
return
end
C
C
C
C
real function t(r,a,ala,alp)
t=atan((r+ala*(1.-cos(a)))/sqrt(ala**2-(r+ala*(1.-cos(a)))
**2))
return
end
real function a(z,t,ala,alp)
a=atan((z+alp*(1.-cos(t)))/sqrt(ala**2-(z+alp*(1.-cos(t)))
**2))
return
end
real function r(alfa,teta,ala,alp)
r=alp*sin(teta)-ala*(1.-cos(alfa))
return
end
real function z(alfa,teta,ala,alp)

```

return
end

al1,al2,al3,vnoll,stig,alp,ala,anvarv,astart ,astopp,tstart,tstopp,,noll,znoll
 ikorrektionstabell for korning vertikalt sid 1

nalfa=laget hos alfa-motorn fran alfa=0 (inkreament)
 dif =erforderling korection hos teta-motorn
 tabellen innehailler inalfa-varden

nalfa dif

0		400		800		1200		1600	
16	0	416	2	816	4	1216	5	1616	8
32	0	432	2	832	4	1232	6	1632	8
48	0	448	2	848	4	1248	6	1648	8
64	0	464	2	864	4	1264	6	1664	8
80	0	480	2	880	4	1280	6	1680	8
96	0	496	2	896	4	1296	6	1696	8
112	0	512	2	912	4	1312	6	1712	8
128	1	528	2	928	4	1328	6	1728	8
144	1	544	2	944	4	1344	6	1744	8
160	1	560	2	960	4	1360	6	1760	8
176	1	576	2	976	4	1376	6	1776	9
192	1	592	3	992	4	1392	6	1792	9
208	1	608	3	1008	4	1408	6	1808	9
224	1	624	3	1024	4	1424	7	1824	9
240	1	640	3	1040	5	1440	7	1840	9
256	1	656	3	1056	5	1456	7	1856	9
272	1	672	3	1072	5	1472	7	1872	9
288	1	688	3	1088	5	1488	7	1888	9
304	1	704	3	1104	5	1504	7	1904	9
320	1	720	3	1120	5	1520	7	1920	9
336	1	736	3	1136	5	1536	7	1936	10
352	1	752	3	1152	5	1552	7	1952	10
368	2	768	3	1168	5	1568	7	1968	10
384	2	784	3	1184	5	1584	7	1984	10
	2		3		5		7		10

ikorrektionstabell for korning vertikalt sid 2

nalfa dif

2000		0		0		0		0	
2016	10	0	0	0	0	0	0	0	0
2032	10	0	0	0	0	0	0	0	0
2048	10	0	0	0	0	0	0	0	0
2064	11	0	0	0	0	0	0	0	0
2080	11	0	0	0	0	0	0	0	0
2096	11	0	0	0	0	0	0	0	0
2112	11	0	0	0	0	0	0	0	0
2128	11	0	0	0	0	0	0	0	0

17

2144	11	0	0	0	0	0	0	0	0
2160	11	0	0	0	0	0	0	0	0
2176	12	0	0	0	0	0	0	0	0
2192	12	0	0	0	0	0	0	0	0
2208	12	0	0	0	0	0	0	0	0
2224	12	0	0	0	0	0	0	0	0
2240	12	0	0	0	0	0	0	0	0
2256	12	0	0	0	0	0	0	0	0
2272	0	0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0	0	0

1korrektionstabell for korning horisontellt sid 1

nteta=laget hos teta-motorn fran teta=0 (inkrement)
dif =erforderling korrektion hos alfa-motorn tabellen innehallar 218nteta-var den

nteta	dif
0	0
16	0
32	0
48	0
64	0
80	0
96	0
112	0
128	0
144	0
160	0
176	0
192	0
208	0
224	0
240	0
256	1
272	1
288	1
304	1
320	1
336	1
352	1
368	1
384	1
400	1
416	1
432	1
448	1
464	1
480	1
496	1
512	1
528	1
544	1
560	1
576	1
592	1
608	1
624	1
640	1
656	1
672	1
688	1
704	1
720	1
736	1
752	2
768	2
784	2
800	2
816	2
832	2
848	2
864	2
880	2
896	2
912	2
928	2
944	2
960	2
976	2
992	2
1008	2
1024	2
1040	2
1056	2
1072	2
1088	2
1104	2
1120	2
1136	2
1152	2
1168	2
1184	2
1200	3
1216	3
1232	3
1248	3
1264	3
1280	3
1296	3
1312	3
1328	3
1344	3
1360	3
1376	3
1392	3
1408	3
1424	3
1440	3
1456	3
1472	3
1488	3
1504	3
1520	3
1536	3
1552	3
1568	3
1584	3
1600	4
1616	4
1632	4
1648	4
1664	4
1680	4
1696	4
1712	4
1728	4
1744	4
1760	4
1776	4
1792	4
1808	4
1824	4
1840	4
1856	4
1872	4
1888	4
1904	4
1920	4
1936	4
1952	4
1968	4
1984	4

1korrektionstabell for korning horisontellt sid 2

nteta dif

2000		2400		2800		3200	0	0
2016	4	2416	6	2816	7	3216	8	0
2032	5	2432	6	2832	7	3232	8	0
2048	5	2448	6	2848	7	3248	8	0
2064	5	2464	6	2864	7	3264	8	0
2080	5	2480	6	2880	7	3280	8	0
2096	5	2496	6	2896	7	3296	8	0
2112	5	2512	6	2912	7	3312	8	0
2128	5	2528	6	2928	7	3328	8	0
2144	5	2544	6	2944	7	3344	9	0
2160	5	2560	6	2960	7	3360	9	0
2176	5	2576	6	2976	7	3376	9	0
2192	5	2592	6	2992	7	3392	9	0
2208	5	2608	6	3008	7	3408	9	0
2224	5	2624	6	3024	7	3424	9	0
2240	5	2640	6	3040	7	3440	9	0
2256	5	2656	6	3056	8	3456	9	0
2272	5	2672	6	3072	8	3472	0	0
2288	5	2688	6	3088	8	0	0	0
2304	5	2704	6	3104	8	0	0	0
2320	5	2720	6	3120	8	0	0	0
2336	5	2736	7	3136	8	0	0	0
2352	5	2752	7	3152	8	0	0	0
2368	5	2768	7	3168	8	0	0	0
2384	6	2784	7	3184	8	0	0	0

Iradiell avvikelse de'r i mm vid korning
vertikalt med korrektion enligt den be-
räknade tabellen

radie= 0.

z= 279.63	deir= .00
255.16	.03
230.95	.05
206.95	.09
183.10	.12
159.39	.09
135.80	.07
112.30	.10
88.91	.07
65.60	.00
42.38	-.08
19.23	.01

19

z= 267.85 delr= .00
244.93 -.10
222.06 -.21
199.19 -.28
176.31 -.35
153.43 .48
130.54 -.59
107.62 -.63
84.68 -.72
61.73 -.83
38.75 -.95
15.73 -.88

1

radie= 113.

z= 248.06 delr= .00
226.87 -.14
205.47 -.30
183.85 -.44
162.03 -.57
140.07 -.75
117.93 -.92
95.63 -1.00
73.19 -1.13
50.62 -1.27
27.92 -1.41
5.03 -1.35

radie= 170.

z= 219.03 delr= .00
199.84 -.06
180.12 -.18
159.92 -.29
139.32 -.41
118.38 -.60
97.11 -.77
75.49 -.86
53.62 -1.00
31.48 1.16
9.07 -1.30
-13.66 -1.24

1

radie= 226.

z= 178.45	delr= .00
161.68	.21
143.99	.27
125.49	.32
106.33	.30
86.61	.26
66.35	.09
45.55	.04
24.33	-.07
2.69	-.21
-17.36	-.33
-41.92	-.27

i vertikal avvikelse delz 1 mm vid korning
horisontellt med korrektion enligt den be-
räknade tabeller

i

z= 283.

r= -62.77	delz= .00
-38.07	-.28

nteta dif

nteta dif

nteta dif

nteta dif

nteta dif

nteta dif

nteta dif

nteta dif

nteta dif

nteta dif

z= 186.

r=	-26.35	delz=	.00
	-1.56		-.31
	22.83		-.01
	46.96		.23
	70.82		.23
	94.05		.83
	116.68		1.47
	138.59		2.08
	159.51		2.87
	179.12		3.91
	196.94		5.59

nteta dif

z= 89.

r=	-5.93	delz=	.00
	18.92		-.32
	43.69		-.10
	68.43		.00
	93.11		-.18
	117.53		.15
	141.67		.41
	165.41		.54
	188.56		.69
	210.93		.87
	232.18		1.35
	252.04		1.87

z= -8.

r= -.05 delz= .00

nteta dif

nteta dif

nteta dif

	100.64		-.36
	126.08		-.16
	151.49		.05

176.75	-.12
201.73	-.23
226.26	-.38
250.10	-.35
273.01	-.42

1

z= -105.

= -8 32 delz= .00

nteta dif

nteta dif

nteta dif

nteta dif

nteta dif

nteta dif

nteta dif

nteta dif

nteta dif

nteta dif

nteta dif

antal inkrement nalfa och nteta som funktion
av resp vinkel

alfa	nalfa	teta	nteta
25	2265	40	3471
24	2187	39	3397
23	2107	38	3322
22	2025	37	3246
21	1943	36	3169
20	1859	35	3092
19	1773	34	3014
18	1687	33	2935
17	1599	32	2856
16	1510	31	2776
15	1420	30	2695
14	1329	29	2613

13	1238	28	2531
12	1146	27	2448
11	1053	26	2364
10	960	25	2280
9	865	24	2195
8	771	23	2110
7	676	22	2023
6	580	21	1937
5	484	20	1849
4	388	19	1761
3	291	18	1673
2	194	17	1584
1	97	16	1494
0	0	15	1404
		14	1314
		13	1222
		12	1131
		11	1039
		10	946
		9	853
		8	760
		7	666
		6	572
		5	477
		4	382
		3	287
		2	192
		1	96
		0	0

al1,al2,al3,vnoll,stig,alp,ala,anvarv,astart ,astopp,tstart,tstopp no ' znoll
 ikorrektionstabell for korning vertikalt sid 1

nalfa=laget hos alfa-potern fran alfa=0 (increment)
 dif =erforderling korektion hos beta-potern
 tabellen innehaller i nalfa-arden

nalfa dif

0	0	400	1	800	2	1200	4	1600	5
16	0	416	1	816	2	1216	4	1616	5
32	0	432	1	832	2	1232	4	1632	5
48	0	448	1	848	3	1248	4	1648	5
64	0	464	1	864	3	1264	4	1664	5
80	0	480	1	880	3	1280	4	1680	5
96	0	496	1	896	3	1296	4	1696	5
112	0	512	2	912	3	1312	4	1712	6
128	0	528	2	928	3	1328	4	1728	6
144	0	544	2	944	3	1344	4	1744	6
160	0	560	2	960	3	1360	4	1760	6
176	0	576	2	976	3	1376	4	1776	6
192	1	592	2	992	3	1392	4	1792	6
208	1	608	2	1008	3	1408	4	1808	6
224	1	624	2	1024	3	1424	4	1824	6
240	1	640	2	1040	3	1440	4	1840	6
256	1	656	2	1056	3	1456	4	1856	6
272	1	672	2	1072	3	1472	5	1872	6
288	1	688	2	1088	3	1488	5	1888	6
304	1	704	2	1104	3	1504	5	1904	6
320	1	720	2	1120	3	1520	5	1920	6
336	1	736	2	1136	3	1536	5	1936	6
352	1	752	2	1152	3	1552	5	1952	7
368	1	768	2	1168	3	1568	5	1968	7
384	1	784	2	1184	4	1584	5	1984	7
	1		2		4		5		7

ikorrektionstabell for korning vertikalt sid 2

nalfa dif

2000	7	0	0	0	0	0	0	0	0
2016	7	0	0	0	0	0	0	0	0
2032	7	0	0	0	0	0	0	0	0

2044	7	0	0	0	0	0	0	0	0
2064	7	0	0	0	0	0	0	0	0
2080	7	0	0	0	0	0	0	0	0
2096	7	0	0	0	0	0	0	0	0
2112	7	0	0	0	0	0	0	0	0
2128	8	0	0	0	0	0	0	0	0
2144	8	0	0	0	0	0	0	0	0
2160	8	0	0	0	0	0	0	0	0
2176	8	0	0	0	0	0	0	0	0
2192	8	0	0	0	0	0	0	0	0
2208	8	0	0	0	0	0	0	0	0
2224	8	0	0	0	0	0	0	0	0
2240	8	0	0	0	0	0	0	0	0
2256	8	0	0	0	0	0	0	0	0
2272	0	0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0	0	0

1korrektionstabell for korning horisontelt

sid 1

nteta=laget hos teta-motorn fran teta=0 (inkrement)
 dif =erforderling korrektion hos alfa-motorn tabellen innehalte: 218nteta-varden

nteta	dif								
0	0	400	1	800	2	1200	4	1600	5
16	0	416	1	816	3	1216	4	1616	5
32	0	432	1	832	3	1232	4	1632	5
48	0	448	1	848	3	1248	4	1648	5
64	0	464	1	864	3	1264	4	1664	5
80	0	480	1	880	3	1280	4	1680	5
96	0	496	1	896	3	1296	4	1696	5
112	0	512	2	912	3	1312	4	1712	6
128	0	528	2	928	3	1328	4	1728	6
144	0	544	2	944	3	1344	4	1744	6
160	0	560	2	960	3	1360	4	1760	6
176	0	576	2	976	3	1376	4	1776	6
192	1	592	2	992	3	1392	4	1792	6
208	1	608	2	1008	3	1408	4	1808	6
224	1	624	2	1024	3	1424	5	1824	6
240	1	640	2	1040	3	1440	5	1840	6
256	1	656	2	1056	3	1456	5	1856	6
272	1	672	2	1072	3	1472	5	1872	6
288	1	688	2	1088	3	1488	5	1888	6
304	1	704	2	1104	3	1504	5	1904	6
320	1	720	2	1120	3	1520	5	1920	6

33.	1	737	2	1136	4	1536	5	1936	6
352	1	752	2	1152	4	1552	5	1952	6
368	1	768	2	1168	4	1568	5	1968	7
384	1	784	2	1184	4	1584	5	1984	7

1korrektionstabell for korning horisontelt

sid 2

nteta dif

2000	7	2400	8	2800	10	3200	12	0	0
2016	7	2416	8	2816	10	3216	12	0	0
2032	7	2432	8	2832	10	3232	12	0	0
2048	7	2448	8	2848	10	3248	12	0	0
2064	7	2464	8	2864	10	3264	12	0	0
2080	7	2480	9	2880	10	3280	12	0	0
2096	7	2496	9	2896	10	3296	12	0	0
2112	7	2512	9	2912	10	3312	12	0	0
2128	7	2528	9	2928	11	3328	12	0	0
2144	7	2544	9	2944	11	3344	12	0	0
2160	7	2560	9	2960	11	3360	13	0	0
2176	7	2576	9	2976	11	3376	13	0	0
2192	7	2592	9	2992	11	3392	13	0	0
2208	7	2608	9	3008	11	3408	13	0	0
2224	8	2624	9	3024	11	3424	13	0	0
2240	8	2640	9	3040	11	3440	13	0	0
2256	8	2656	9	3056	11	3456	13	0	0
2272	8	2672	9	3072	11	3472	0	0	0
2288	8	2688	9	3088	11	0	0	0	0
2304	8	2704	10	3104	11	0	0	0	0
2320	8	2720	10	3120	11	0	0	0	0
2336	8	2736	10	3136	11	0	0	0	0
2352	8	2752	10	3152	12	0	0	0	0
2368	8	2768	10	3168	12	0	0	0	0
2384	8	2784	10	3184	12	0	0	0	0

irradiell avvikelse delr i m vid korning vertikalt sed korrektion enlgt den beraknade tabellen

radie= 0.

z= 281.11	delr= .00
250.15	.05
231.59	.06
207.35	-.01
183.34	.10
159.52	.26
135.87	1.0

27

88.92	.27
65.61	.06
42.38	.24
19.23	-.03

radie= 92.

z= 265.88	delr= .00
242.58	-.11
219.47	-.25
196.47	-.46
173.51	-.47
150.57	-.42
127.69	-.62
104.77	-.62
81.85	-.65
58.95	-.91
35.96	-.76
13.00	-1.05

1

radie= 104.

z= 236.84	delr= .00
215.40	-.18
193.87	-.39
172.25	-.67
150.44	-.75
128.47	-.76
106.43	-1.01
84.19	-1.06
61.81	-1.12
39.35	-1.42
16.62	-1.29
-6.14	-1.60

radie= 276

z= 191.93	delr= .00
172.63	-.11
152.94	-.28
132.90	.53
112.40	.59
91.54	-.60
70.47	.85
49.00	-.90

27.23	-1.57
5.27	-1.27
-17.16	-1.14
-39.69	-1.46

i

radie= 368.

z= 126.98	delr= .0^
110.32	.18
92.87	.24
74.76	.16
55.86	.24
36.34	.34
16.43	.18
-4.12	.18
-25.15	.17
-46.50	-.09
-68.58	.05
-90.83	-.24

i vertikal afvikelse delz i mm ved korning
 horisontelt med korrektion enligt den be-
 räknade tabellen

i

z= 283.

r= -62.77 delz= .00

nteta dif

nteta dif

nteta dif

nteta dif

nteta dif

nteta dif

nteta dif

nteta dif

nteta dif

nteta dif

nteta dif

z= 173.

r=	-22.77	delz=	.00
	14.03		-.02
	50.50		.12
	86.56		.36
	122.07		.76
	156.87		1.26
	190.67		2.04
	223.17		3.04
	253.93		4.38
	282.29		6.34

nteta dif

nteta dif

z= 63.

r=	-2.77	delz=	.00
	33.77		.06
	71.03		.02
	108.08		.03
	145.02		.15
	181.72		.23
	217.97		.43
	253.56		.64
	288.18		.84
	321.42		1.15
	352.70		1.83
	381.47		2.37

z= -47.

r= -1.63 delz= .00

nteta dif

nteta dif

nteta dif

nteta dif

nteta dif

nteta dif

264.01 -.34

301.68 -.54

338.57 -.77

374.25 -.87

408.26 -1.43

i

z= -157.

r= -18.59 delz= .00

nteta dif

nteta dif

nteta dif

nteta dif

nteta dif

nteta dif

nteta dif

nteta dif

nteta dif

nteta dif

nteta dif

lanttal inkrement nalfa och nteta sum funtio
av resp vinkei

alfa	nalfa	teta	nteta
25	2265	40	3471
24	2187	39	3397
23	2107	38	3322
22	2025	37	3246
21	1943	36	3169
20	1859	35	3092
19	1773	34	3014
18	1687	33	2935
17	1599	32	2856
16	1510	31	2776
15	1420	30	2695
14	1330	29	2613
13	1238	28	2531
12	1146	27	2448
11	1053	26	2364
10	960	25	2280
9	865	24	2195
8	771	23	2110
7	676	22	2023
6	580	21	1937
5	484	20	1849
4	388	19	1761
3	291	18	1673
2	194	17	1584
1	97	16	1494
0	0	15	1404
		14	1314
		13	1222
		12	1131
		11	1039
		10	946
		9	853
		8	760
		7	666
		6	572
		5	477
		4	382
		3	287
		2	192
		1	96
		0	0

al1,al2,al3,vnoll,stig a.p,ala,anvarv,asta t ,astopp,tstart,tstopp,rnoi,znoll,rmin, max,zmin,zmax
 lkorrekt,ontabell for korning vertikalt sid 1

nalfa=laget hos alfa-motorn fran alfa=0 inkrement
 dif =erforderling korektion hos seta-motorn
 tabellen innehaier nalfa-varde

nalfa dif

-3744		-3344	-2744	-2544	-2144	
19	16	14	11	9		
-3728	18	-3328	-2928	-2528	-2128	9
-3712	18	-3312	-2912	-2512	-2112	9
-3696	18	-3296	-2896	-2496	-2096	9
-3680	18	-3280	-2880	-2480	-2080	9
-3664	18	-3264	-2864	-2464	-2064	9
-3648	18	-3248	-2848	-2448	-2048	9
-3632	18	-3232	-2832	-2432	-2032	9
-3616	18	-3216	-2816	-2416	-2016	9
-3600	18	-3200	-2800	-2400	-2000	9
-3584	17	-3184	-2784	-2384	-1984	9
-3568	17	-3168	-2768	-2368	-1968	9
-3552	17	-3152	-2752	-2352	-1952	8
-3536	17	-3136	-2736	-2336	-1936	8
-3520	17	-3120	-2720	-2320	-1920	8
-3504	17	-3104	-2704	-2304	-1904	8
-3488	17	-3088	-2688	-2288	-1888	8
-3472	17	-3072	-2672	-2272	-1872	8
-3456	17	-3056	-2656	-2256	-1856	8
-3440	17	-3040	-2640	-2240	-1840	8
-3424	16	-3024	-2624	-2224	-1824	8
-3408	16	-3008	-2608	-2208	-1808	8
-3392	16	-2992	-2592	-2192	-1792	8
-3376	16	-2976	-2576	-2176	-1776	8
-3360	16	-2960	-2560	-2160	-1760	8
	16	14	11	9	8	

lkorrekt,ontabell for korning vertikalt

sid 2

nalfa dif

-1744	7	-1344	-944	-544	-144	1
-1728	7	-1328	-928	-528	-128	1
-1712	7	-1312	-912	-512	-112	1
-1696	7	-1296	-896	-496	-96	0
-1680	7	-1280	-880	-480	-80	0
-1664	7	-1264	-864	-464	-64	0
-1648	7	-1248	-848	-448	-48	0
-1632	7	-1232	-832	-432	-32	0
-1616	7	-1216	-816	-416	-16	0

-1600	7	-1200	5	-800	3	-400	2	0	0
-1584	7	-1184	5	-784	3	-384	2	0	0
-1568	7	-1168	5	-768	3	-368	2	0	0
-1552	7	-1152	5	-752	3	-352	2	0	0
-1536	7	-1136	5	-736	3	-336	1	0	0
-1520	7	-1120	5	-720	3	-320	1	0	0
-1504	6	-1104	5	-704	3	-304	1	0	0
-1488	6	-1088	5	-688	3	-288	1	0	0
1472	6	-1072	5	-672	3	-272	1	0	0
-1456	6	-1056	4	-656	3	-256	1	0	0
-1440	6	-1040	4	-640	3	-240	1	0	0
-1424	6	-1024	4	-624	3	-224	1	0	0
-1408	6	-1008	4	-608	3	-208	1	0	0
-1392	6	-992	4	-592	3	-192	1	0	0
-1376	6	-976	4	-576	2	-176	1	0	0
-1360	6	-960	4	-560	2	-160	1	0	0
	6		4		2		1		0

korrektionstabell for korning horisontellt sid 1

nteta=laget hos beta-motor fra beta=0 (inkrement)
dif =erforderling korrektion hos alfa-motor; tabellen inneholder 218 beta-varden

nteta	dif								
0	0	400	-1	800	-2	1200	-3	1600	-3
16	0	416	-1	816	-2	1216	-3	1616	-4
32	0	432	-1	832	-2	1232	-3	1632	-4
48	0	448	-1	848	-2	1248	-3	1648	-4
64	0	464	-1	864	-2	1264	-3	1664	-4
80	0	480	-1	880	-2	1280	-3	1680	-4
96	0	496	-1	896	-2	1296	-3	1696	-4
112	0	512	-1	912	-2	1312	-3	1712	-4
128	0	528	-1	928	-2	1328	-3	1728	-4
144	0	544	-1	944	-2	1344	-3	1744	-4
160	0	560	-1	960	-2	1360	-3	1760	-4
176	0	576	-1	976	-2	1376	-3	1776	-4
192	0	592	-1	992	-2	1392	-3	1792	-4
208	0	608	-1	1008	-2	1408	-3	1808	-4
224	0	624	-1	1024	-2	1424	-3	1824	-4
240	0	640	-1	1040	-2	1440	-3	1840	-4
256	0	656	-1	1056	-2	1456	-3	1856	-4
272	-1	672	-1	1072	-2	1472	-3	1872	-4
288	-1	688	-1	1088	-2	1488	-3	1888	-4
304	-1	704	-1	1104	-2	1504	-3	1904	-4
320	-1	720	-1	1120	-2	1520	-3	1920	-4
336	-1	736	-1	1136	-2	1536	-3	1936	-4
352	-1	752	-2	1152	-2	1552	-3	1952	-4
368	-1	768	-2	1168	-2	1568	-3	1968	-4
384	-1	784	-2	1184	-2	1584	-3	1984	-4
	-1		-2		-3		-3		-4

korrektionstabelle for korning horisontellt sid 2

34

nteta dif

2000	2400	2800	3200	0	0
-5	-6	-7	-8	0	0
2016	2416	2816	3216	0	0
-5	-6	-7	-8	0	0
2032	2432	2832	3232	0	0
-5	-6	-7	-8	0	0
2048	2448	2848	3248	0	0
-5	-6	-7	-8	0	0
2064	2464	2864	3264	0	0
-5	-6	-7	-8	0	0
2080	2480	2880	3280	0	0
-5	-6	-7	-9	0	0
2096	2496	2896	3296	0	0
-5	-6	-7	-9	0	0
2112	2512	2912	3312	0	0
-5	-6	-7	-9	0	0
2128	2528	2928	3328	0	0
-5	-6	-7	-9	0	0
2144	2544	2944	3344	0	0
-5	-6	-7	-9	0	0
2160	2560	2960	3360	0	0
-5	-6	-7	-9	0	0
2176	2576	2976	3376	0	0
-5	-6	-7	-9	0	0
2192	2592	2992	3392	0	0
-5	-6	-7	-9	0	0
2208	2608	3008	3408	0	0
-5	-6	-8	-9	0	0
2224	2624	3024	3424	0	0
-5	-6	-8	-9	0	0
2240	2640	3040	3440	0	0
-5	-6	-8	-9	0	0
2256	2656	3056	3456	0	0
-5	-6	-8	-9	0	0
2272	2672	3072	3472	0	0
-5	-6	-8	0	0	0
2288	2688	3088	0	0	0
-5	-6	-8	0	0	0
2304	2704	3104	0	0	0
-5	-7	-8	0	0	0
2320	2720	3120	0	0	0
-5	-7	-8	0	0	0
2336	2736	3136	0	0	0
-5	-7	-8	0	0	0
2352	2752	3152	0	0	0
-5	-7	-8	0	0	0
2368	2768	3168	0	0	0
-6	-7	-8	0	0	0
2384	2784	3184	0	0	0
-6	-7	-8	0	0	0

1rad. ell. afvikelse delr i mm vid korning
vertikalt med korrektion enligt den be-
ræknede tabellen

radie= -157.

z=	-28.18	delr=	.00
	-67.98		311.11
	-106.61		303.62
	-144.27		291.36
	-181.01		274.14
	-216.89		251.76
	-252.11		224.16
	-286.84		191.21
	-321.27		152.5
	-355.70		107.99
	-390.45		57.26
	-425.92		.01

z= -42.02 delr= .00
-81.71 377.37
-119.98 369.88
-157.07 357.62
-193.02 340.39
-227.89 317.99
-261.90 290.35
-295.23 257.32
-328.05 218.51
-360.70 173.83
-393.48 122.88
-426.79 65.34

!

radie= -223.

z= -59.14 delr= .00
-98.71 443.62
-136.59 436.15
-173.06 423.91
-208.14 406.71
-241.93 384.33
-274.63 356.69
-306.44 323.65
-337.55 284.78
-368.31 239.99
-399.00 188.87
-430.04 131.08

radie= -256.

z= -80.00 delr= .00
-119.43 509.89
-156.88 502.45
-192.65 490.27
-226.79 473.13
-259.37 450.82
-290.63 423.24
-320.80 390.24
-350.04 351.37
-378.74 306.54
-407.20 255.31
-435.83 197.34

!

radie= -287.

z= -105.28 delz= .00

-144.56 576.16

-181.50 568.79

-216.49 556.70

-249.55 539.69

-280.77 517.50

-310.42 490.06

-338.75 457.17

-365.94 418.39

-392.30 373.59

-418.41 322.33

-444.43 264.25

i vertikal afvikelse delz i m ved korning
horisontelt med korrektion enligt den be-
raknade tabellen

i

z= -105.

r= -8.32 delz= .00

nteta dif

nteta dif

nteta dif

nteta dif

nteta dif

nteta dif

nteta dif

nteta dif

nteta dif

nteta dif

nteta dif

z= 29.

r=	-.62	delz=	.00
	24.27		-58.46
	49.25		-62.83
	74.33		-69.97
	99.47		-79.81
	124.54		-93.26
	149.48		-109.92
	174.19		-130.00
	198.53		-153.71
	222.99		-181.43
	245.24		-213.53
	267.09		-250.42

z= 163.

r=	-20.05	delz=	.00
	4.75		-326.43
	29.28		-330.76
	53.63		-337.83
	77.79		-347.59
	101.47		-360.92
	124.71		-377.42
	147.36		-397.30
	169.25		-420.78
	190.14		-448.20
	209.73		-479.94
	227.64		-516.38

z= 297.

r=	-69.27	delz=	.00
	-44.54		-594.39
	-20.52		-598.65
	3.02		-605.61
	26.10		-615.21
	48.24		-628.30
	69.57		-644.51
	89.91		-664.03
	109.05		-687.05
	126.68		-713.90
	142.41		-744.92
	157.57		-780.11

1
z= 431.

r= -156.75 delz= 00
-132.12 -862.34

nteta dif

nteta dif

nteta dif

nteta dif

nteta dif

nteta dif

nteta dif

nteta dif

nteta dif

nteta dif

antal inkrement nalfa och nteta som funktion
av resp vinkel

alfa nalfa teta nteta

al1,al2,al3,vnoll,stig,s'p,ala,anvarv,astart ,astopp,tstart,tstopp, noll,znoll, min,max,zmin,zma.
 lkorrektiontabe'' for korning vertikalt sid 1

nalfa=laget hos alfa-motorn fran alfa=0 (inkrement,
 dif =erforderling korektion hos teta-motorn
 tabellen inneha'ller inalfa-warden

nalfa dif

-3744		-3344		-2944		-2544		-2144	
12		11		9		8		6	
-3728	12	-3328	10	-2928	9	-2528	8	-2128	6
-3712	12	-3312	10	-2912	9	-2512	7	-2112	6
-3696	12	-3296	10	-2896	9	-2496	7	-2096	6
-3680	12	-3280	10	-2880	9	-2480	7	-2080	6
-3664	12	-3264	10	-2864	9	-2464	7	-2064	6
-3648	12	-3248	10	-2848	9	-2448	7	-2048	6
-3632	12	-3232	10	-2832	9	-2432	7	-2032	6
-3616	12	-3216	10	-2816	9	-2416	7	-2016	6
-3600	12	-3200	10	-2800	8	-2400	7	-2000	6
-3584	11	-3184	10	-2784	8	-2384	7	-1984	6
-3568	11	-3168	10	-2768	8	-2368	7	-1968	6
-3552	11	-3152	10	-2752	8	-2352	7	-1952	6
-3536	11	-3136	10	-2736	8	-2336	7	-1936	6
-3520	11	-3120	10	-2720	8	-2320	7	-1920	6
-3504	11	-3104	10	-2704	8	-2304	7	-1904	5
-3488	11	-3088	10	-2688	8	-2288	7	-1888	5
-3472	11	-3072	10	-2672	8	-2272	7	-1872	5
-3456	11	-3056	9	-2656	8	-2256	7	-1856	5
-3440	11	-3040	9	-2640	8	-2240	7	-1840	5
-3424	11	-3024	9	-2624	8	-2224	7	-1824	5
-3408	11	-3008	9	-2608	8	-2208	6	-1808	5
-3392	11	-2992	9	-2592	8	-2192	6	-1792	5
-3376	11	-2976	9	-2576	8	-2176	6	-1776	5
-3360	11	-2960	9	-2560	8	-2160	6	-1760	5
	11		9		8		6		5

l orrektiontabell for korning vertikalt sid 2

nalfa dif

-1744		-1344		-944		-544		-144	
5		4		3		2		0	
-1728	5	-1328	4	-928	3	-528	1	-128	0
-1712	5	-1312	4	-912	3	-512	1	-112	0
-1696	5	296	4	-896	3	-496	1	-96	0
-1680	5	-1280	4	-880	2	-480	1	-80	0
-1664	5	-1264	4	-864	2	-464	1	-64	0
-1648	5	-1248	4	-848	2	-448	1	-48	0
-1632	5	-1232	4	-832	2	-432	1	-32	0
-1616	5	-1216	3	-816	2	-416	1	-16	0

-1600	5	-1200	3	-800	2	-400	1	0
-1584	5	-1184	3	-784	2	-384	1	0
-1568	4	-1168	3	-768	2	-368	1	0
1552	4	-1152	3	-752	2	-352	1	0
-1536	4	-1136	3	-736	2	-336	1	0
-1520	4	-1120	3	-720	2	-320	1	0
1504	4	-1104	3	-704	2	-304	1	0
-1488	4	1088	3	-688	2	-288	1	0
-1472	4	-1072	3	-672	2	-272	1	0
-1456	4	-1056	3	-656	2	-256	1	0
-1440	4	-1040	3	-640	2	-240	1	0
-1424	4	-1024	3	-624	2	-224	1	0
-1408	4	-1008	3	-608	2	-208	1	0
-1392	4	-992	3	-592	2	-192	1	0
-1376	4	-976	3	-576	2	-176	1	0
-1360	4	-960	3	-560	2	-160	0	0
	4		3		2		0	0

korrektionstabell for korning horisontellt sid 1

nteta=laget hos teta-notorn fran teta=0 (inkrement)
dif =erforderling korrektion hos alfa-notorn tabellen inneholder 218nteta-warden

nteta	dif								
0	0	400	-1	800	-2	1200	-4	1600	-5
16	0	416	-1	816	-3	1216	-4	1616	-5
32	0	432	-1	832	-3	1232	-4	1632	-5
48	0	448	-1	848	-3	1248	-4	1648	-5
64	0	464	-1	864	-3	1264	-4	1664	-5
80	0	480	-1	880	-3	1280	-4	1680	-5
96	0	496	-2	896	-3	1296	-4	1696	-6
112	0	512	-2	912	-3	1312	-4	1712	-6
128	0	528	-2	928	-3	1328	-4	1728	-6
144	0	544	-2	944	-3	1344	-4	1744	-6
160	0	560	-2	960	-3	1360	-4	1760	-6
176	-1	576	-2	976	-3	1376	-4	1776	-6
192	-1	592	-2	992	-3	1392	-4	1792	-6
208	-1	608	-2	1008	-3	1408	-4	1808	-6
224	-1	624	-2	1024	-3	1424	-5	1824	-6
240	-1	640	-2	1040	-3	1440	-5	1840	-6
256	-1	656	-2	1056	-3	1456	-5	1856	-6
272	-1	672	-2	1072	-3	1472	-5	1872	-6
288	-1	688	-2	1088	-3	1488	-5	1888	-6
304	-1	704	-2	1104	-3	1504	-5	1904	-6
320	-1	720	-2	1120	-4	1520	-5	1920	-6
336	-1	736	-2	1136	-4	1536	-5	1936	-6
352	-1	752	-2	1152	-4	1552	-5	1952	-7
368	-1	768	-2	1168	-4	1568	-5	1968	-7
384	-1	784	-2	1184	-4	1584	-5	1984	-7
	-1		-2		-4		-5		-7

korrektionstabell for korning horisontellt sid 2

41

nteta dif

2000		2400		2800		3200		0	
-7	-8		-10		-12			0	0
2016		2416		2816		3216		0	0
-7	-8		-10		-12			0	0
2032		2432		2832		3232		0	0
-7	-9		-10		-12			0	0
2048		2448		2848		3248		0	0
-7	-9		-10		-13			0	0
2064		2464		2864		3264		0	0
-7	-9		-11		-13			0	0
2080		2480		2880		3280		0	0
-7	-9		-11		-13			0	0
2096		2496		2896		3296		0	0
-7	-9		-11		-13			0	0
2112		2512		2912		3312		0	0
-7	-9		-11		-13			0	0
2128		2528		2928		3328		0	0
-7	-9		-11		-13			0	0
2144		2544		2944		3344		0	0
-7	-9		-11		-13			0	0
2160		2560		2960		3360		0	0
-7	-9		-11		-13			0	0
2176		2576		2976		3376		0	0
-7	-9		-11		-13			0	0
2192		2592		2992		3392		0	0
-8	-9		-11		-13			0	0
2208		2608		3008		3408		0	0
-8	-9		-11		-14			0	0
2224		2624		3024		3424		0	0
-8	-9		-11		-14			0	0
2240		2640		3040		3440		0	0
-8	-9		-11		-14			0	0
2256		2656		3056		3456		0	0
-8	-10		-12		-14			0	0
2272		2672		3072		3472		0	0
-8	-10		-12		0			0	0
2288		2688		3088		0		0	0
-8	-10		-12		0			0	0
2304		2704		3104		0		0	0
-8	-10		-12		0			0	0
2320		2720		3120		0		0	0
-8	-10		-12		0			0	0
2336		2736		3136		0		0	0
-8	-10		-12		0			0	0
2352		2752		3152		0		0	0
-8	-10		-12		0			0	0
2368		2768		3168		0		0	0
-8	-10		-12		0			0	0
2384		2784		3184		0		0	0
-8	-10		-12		0			0	0

irradiell avvikelse delr i mm vid korning
vertikalt med korrektion enligt den be-
ræknade tabellen

radie= -157.

z= -18.59 delr= .00

-58.53	311.04
-97.69	303.68
-136.11	291.42
-173.85	274.24
-210.96	251.97
-247.52	224.57
-283.59	191.73
-319.31	153.38
-354.83	109.31
-390.28	59.06
-425.91	2.30

z= -38.99 delr= .00
-78.78 448.00
-117.50 440.62
-155.19 428.32
-191.93 411.08
-227.74 388.74
-262.73 361.23
-296.95 328.25
-336.54 289.71
-363.67 245.40
-396.44 194.84
-429.09 137.68

1

radie= -294.

z= -67.81 delr= .00
-107.43 584.96
-145.66 577.58
-182.55 565.29
-218.17 548.05
-252.56 525.69
-285.83 498.15
-318.02 465.11
-349.31 426.47
-379.85 382.01
-409.74 331.24
-439.21 273.79

radie= -362

z= -106.33 delr= .00
-145.77 721.93
-183.45 714.59
-219.42 702.35
-253.78 685.17
-286.56 662.89
-317.89 635.42
-347.81 602.42
-376.52 563.80
-404.19 519.31
-430.91 468.46
-456.91 410.85

1

radie= -431.

z= -156.75 delr= .00

-195.97 858.91

-232.99 851.65

-267.88 839.54

-300.75 822.53

-331.64 800.44

-360.71 773.17

-388.00 740.38

-413.74 701.94

-438.12 657.61

-461.24 606.84

-483.32 549.25

i vertikal afvikelse delz i mm vid korning
horisontelt med korrektion enligt den be-
raknade tabellen

i

z= -157.

r= -18.59 delz= .00

nteta dif

nteta dif

nteta dif

nteta dif

nteta dif

nteta dif

nteta dif

nteta dif

nteta dif

nteta dif

44

nteta dif

z= -10.

r= -.07 delz= .00

nteta dif

nteta dif

nteta dif

147.81	-14.11
187.61	-33.95
225.27	-58.77
262.57	-88.69
299.26	-124.11
334.94	-165.80
369.24	-213.40
401.55	-268.60

z= 137

r= -14.15 delz= .00

22.72	-275.89
59.42	-282.07
95.89	-292.55
132.01	-307.50
167.61	-327.16
202.51	-351.74
236.49	-381.36
269.21	-416.40
300.13	-457.61
328.95	-504.81
354.79	-559.03

z= 284.

r= -63.08 delz= .00

-26.44	-569.57
9.51	-575.65
44.71	-585.96
78.99	-600.66
112.17	-619.97
143.99	-644.09

174.23	-673.13
202.45	707.42
227.93	-747.64
250.38	-793.59
268.60	-846.16

1

z= 431.

r= -156.75 delz= .00

nteta dif

nteta dif

nteta dif

nteta dif

nteta dif

nteta dif

nteta dif

nteta dif

nteta dif

nteta dif

nteta dif

antal inkrement nalfa och nteta som funktion
av resp vinkel

alfa	nalfa	teta	nteta
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