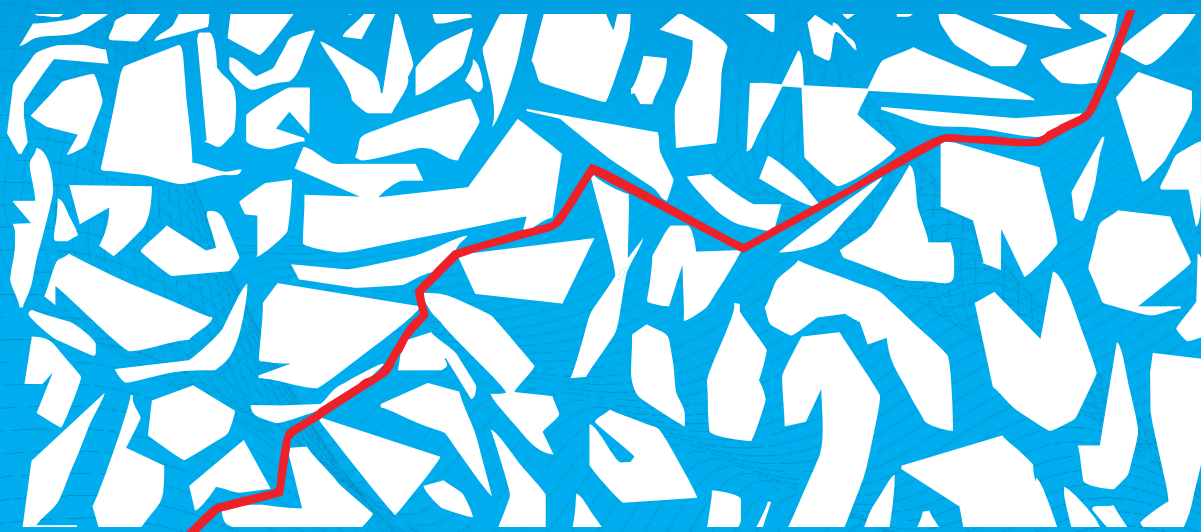


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Piotr Bigaj

Global Path Planning for Mobile Robots